

Recitation 8. May 4

Focus: positive definite/semidefinite matrices, singular value decomposition, pseudo-inverse

If all the eigenvalues (or equivalently, the pivots) of a symmetric matrix S are positive/non-negative, then S is called:

positive definite/semidefinite

We have:

$$S \text{ positive definite} \quad \Leftrightarrow \quad \mathbf{v}^T S \mathbf{v} > 0$$

$$S \text{ positive semidefinite} \quad \Leftrightarrow \quad \mathbf{v}^T S \mathbf{v} \geq 0$$

for any vector $\mathbf{v} \neq 0$. The quantity $\mathbf{v}^T S \mathbf{v}$ is called the energy of \mathbf{v} .

The Singular Value Decomposition (SVD) of a matrix A is a way of writing it as:

$$A = U \Sigma V^T$$

where U and V are orthogonal matrices, and Σ is diagonal. If we let:

$$U = [\mathbf{u}_1 \mid \dots \mid \mathbf{u}_m] \quad \text{and} \quad \Sigma = \begin{bmatrix} \sigma_1 & 0 & 0 & 0 & \dots \\ 0 & \ddots & 0 & 0 & \dots \\ 0 & 0 & \sigma_r & 0 & \dots \\ 0 & 0 & 0 & 0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix} \quad \text{and} \quad V = [\mathbf{v}_1 \mid \dots \mid \mathbf{v}_n]$$

then the SVD is a way of writing A as a sum of rank 1 matrices:

$$A = \sum_{i=1}^r \mathbf{u}_i \sigma_i \mathbf{v}_i^T$$

You may compute the SVD by letting:

- the **right singular vectors** $\mathbf{v}_1, \dots, \mathbf{v}_n$ be the eigenvectors of $A^T A$
- the **left singular vectors** $\mathbf{u}_1, \dots, \mathbf{u}_m$ be the eigenvectors of AA^T
- the **singular values** $\sigma_1, \dots, \sigma_r$ be the square roots of the non-zero eigenvalues of $A^T A$ or AA^T

The pseudo-inverse of A is defined by:

$$A^+ = V \Sigma^+ U^T$$

where Σ^+ has diagonal entries $\frac{1}{\sigma_i}$ instead of σ_i . It is useful because:

the closest $A\mathbf{v}$ can be to a vector \mathbf{b} is achieved for $\mathbf{v} = A^+ \mathbf{b}$

Moreover:

AA^+ is the projection matrix onto $C(A)$

A^+A is the projection matrix onto $C(A^T)$

Also, the SVD allows us to define the polar decomposition of $A = U \Sigma V^T$ as:

$$A = QS$$

where $Q = UV^T$ is orthogonal, and $S = V \Sigma V^T$ is symmetric.

1. Consider the matrices:

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix} \quad C = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

- Say which of them is positive definite, positive semidefinite, or neither.
- Write down the energy of an arbitrary vector $\begin{bmatrix} x \\ y \end{bmatrix}$ with respect to either of these matrices. Setting the energy equal to 1 gives rise to a conic. What kind of conic is it, in each of the three cases?

Solution: The characteristic polynomial of A is $(1 - \lambda)(3 - \lambda) - 1 = \lambda^2 - 4\lambda + 2$. Thus the eigenvalues are $2 \pm \sqrt{2}$, so A is positive definite. The energy is:

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^2 + 2xy + 3y^2 = (x + y)^2 + 2y^2$$

Setting $(x + y)^2 + 2y^2 = 1$ is the equation of an ellipse.

The characteristic polynomial of B is $(3 - \lambda)(-2 - \lambda)$. Thus the eigenvalues are 3 and -2 , so B is not positive (semi)definite. The energy is:

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 3x^2 - 2y^2 =$$

Setting $3x^2 - 2y^2 = 1$ is the equation of a hyperbola.

The characteristic polynomial of C is $(1 - \lambda)^2 - 1$. Thus the eigenvalues are 2 and 0, so C is positive semidefinite. The energy is:

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^2 + 2xy + y^2 = (x + y)^2$$

Setting $(x + y)^2 = 1$ is the equation of a pair of lines.

2. Consider the matrix

$$A = \begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix}$$

- Compute the Singular Value Decomposition of A .
- Compute the pseudo-inverse A^+ . Then compute the inverse A^{-1} by another method. How do they compare?

Solution: First we calculate $A^T A = \begin{bmatrix} 2 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix}$. Next we diagonalize this matrix:

$$\det(A^T A - \lambda I) = \lambda^2 - 10\lambda + 16 \quad \Rightarrow \quad \lambda = 8 \text{ or } 2$$

Moreover, being symmetric, $A^T A$ has orthonormal eigenvectors:

$$N \begin{bmatrix} -3 & 3 \\ 3 & -3 \end{bmatrix} = \mathbb{R} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \Rightarrow \quad \mathbf{v}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad N \begin{bmatrix} 3 & 3 \\ 3 & 3 \end{bmatrix} = \mathbb{R} \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix} \quad \Rightarrow \quad \mathbf{v}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

for $\lambda = 8$ and $\lambda = 2$, respectively. We therefore set:

$$V = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 2\sqrt{2} & 0 \\ 0 & \sqrt{2} \end{bmatrix}$$

Then to find the \mathbf{u}_i , we use the formula:

$$\mathbf{u}_1 = \frac{A\mathbf{v}_1}{\sigma_1} = \frac{1}{\sqrt{2}} \begin{bmatrix} 4 \\ 0 \end{bmatrix} \frac{1}{2\sqrt{2}} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \mathbf{u}_2 = \frac{A\mathbf{v}_2}{\sigma_2} = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 2 \end{bmatrix} \frac{1}{\sqrt{2}} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

So $U = I$ and the full SVD is:

$$A = U\Sigma V^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2\sqrt{2} & 0 \\ 0 & \sqrt{2} \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

The pseudo-inverse is

$$A^+ = V\Sigma^+U^T = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{2\sqrt{2}} & 0 \\ 0 & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{4} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 1 & -2 \\ 1 & 2 \end{bmatrix}$$

Equivalently, we can use the formula for the inverse of a 2×2 matrix to see that:

$$A^{-1} = \frac{1}{4} \begin{bmatrix} 1 & -2 \\ 1 & 2 \end{bmatrix}$$

The phenomenon here is that when a matrix is invertible, its inverse coincides with its pseudo-inverse.

3. • Express the function:

$$\frac{3x^2 + 2xy + 3y^2}{x^2 + y^2} \quad (1)$$

in the form $\frac{\mathbf{v}^T S \mathbf{v}}{\mathbf{v}^T \mathbf{v}}$, where $\mathbf{v} = \begin{bmatrix} x \\ y \end{bmatrix}$ and S is a certain symmetric matrix that you are free to choose. Compute the maximum of (1) in terms of the eigenvalues of S . For what values of (x, y) is the maximum achieved?

- Find the maximum of the function:

$$\sqrt{\frac{(x + 4y)^2}{x^2 + y^2}}$$

by expressing it in the form $\frac{\|A\mathbf{v}\|}{\|\mathbf{v}\|}$ for a suitable matrix A , and then invoking the singular values of A .

Solution:

We can express the numerator as:

$$3x^2 + 2xy + 3y^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

so the required expression is $\frac{\mathbf{v}^T S \mathbf{v}}{\mathbf{v}^T \mathbf{v}}$ for $S = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$. The maximum of the expression is given by the largest eigenvalue of the matrix S , and the maximum is achieved at the corresponding eigenvector. The matrix S has eigenvalues $\lambda = 4$ and $\lambda = 2$ so the maximum is 4. The corresponding eigenvector is $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$. So the minimum is achieved whenever $x = y$, i.e. \mathbf{v} is a multiple of $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

We can express $(x + 4y)^2 = \|A\mathbf{v}\|^2$ for the 1×2 matrix $A = \begin{bmatrix} 1 & 4 \end{bmatrix}$. The expression is maximized by the largest singular value of A (in absolute value), which is the square root of the largest eigenvalue of:

$$A^T A = \begin{bmatrix} 1 & 4 \\ 4 & 16 \end{bmatrix}$$

It's easy to see that the eigenvalues of $A^T A$ are 17 and 0, so the maximum is $\sqrt{17}$.